

Technical data

SCREWDRIVING TECHNOLOGY FOR AUTOMATIC FEEDING

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Handheld Screwdriving



WEBER handheld screwdrivers combine ergonomics and variability in each model. The advantages of the electric and pneumatic handheld screwdrivers are obvious: highly flexible, powerful, and thanks to programmable control nearly 100 percent process-reliable. In addition, ergonomics and variability play a central role in manual fitting with handheld screwdrivers. Weber enables with its products – in particular thanks to their built-in bit stroke – fatigue-free working, while realizing high quantities in extremely short cycle times. Freedom in connection technology, as WEBER understands it.

Long service life thanks to wearresistant surfaces



compact design

 \sim

Economically viable from 20,000 screwdriving operation per year

Low moving mass for short cycle times

Handheld Screwdriving

Overview of handheld screwdrivers

Ergonomics and variability - flexibility in fastening technology

Criteria

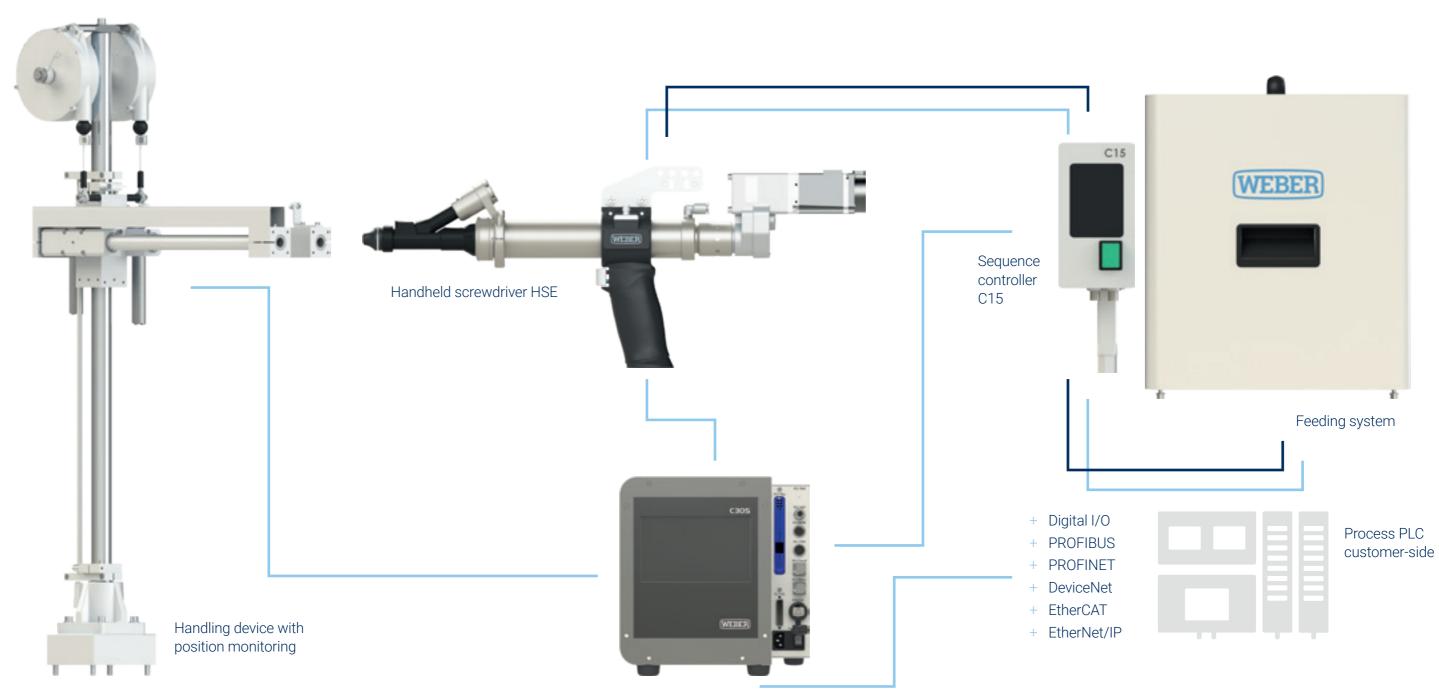
For shank-heavy screws (Head diameter / Shaft length > 1,5 mm)
For head-heavy screws (Head diameter / Shaft length < 1,5 mm)
For nuts
For inserting / press-fitting
Use as a tightening screwdriver
Start trigger
Mechanical shut-off clutch
Integrated auto bit stroke
Quick bit change
With swivel arm principle (Feeding during screwdriving)
For automatic feeding (ZEB / ZEL)
Torque up to [mm]
With electric drive
With pneumatic drive
Option customer-side drive
Option transducer with angle measurement (MDW)
Option integrated reaction transducer (MDG)
Integrated program changeover
Suitable for multi-stage screwdriving programs
Documentation of the screwdriving results
Combination with process controller C30S
Combination with process controller C50S
Combination with sequence controller CU30
Combination with sequence controller C10S
Combination with sequence controller C15S
Option screw bit lock function
Option pistol grip for horizontal screwdriving
Option bit box
Option vacuum version
Option magnetic screwdriving tool
Option redundant measuring according to VDI / VDE 2862 sheet 2 category A
ESD-compliant

HET	HSE	HSP
\checkmark	\checkmark	\checkmark
\checkmark	-	-
\checkmark	\checkmark	-
-	\checkmark	\checkmark
\checkmark	-	-
\checkmark	\checkmark	\checkmark
-	-	\checkmark
-	\checkmark	\checkmark
\checkmark	-	\checkmark
-	\checkmark	\checkmark
-	\checkmark	\checkmark
30	10	5,3
\checkmark	\checkmark	-
-	-	\checkmark
\checkmark	\checkmark	-
-	\checkmark	-
-	-	\checkmark
-	\checkmark	\checkmark
-	\checkmark	-
-	\checkmark	\checkmark
\checkmark	-	-
\checkmark	\checkmark	-
\checkmark	\checkmark	\checkmark
\checkmark	\checkmark	-
\checkmark	\checkmark	\checkmark

Handheld Screwdriving

System overview

Typical handheld screwdriver set up in your workstation



Process controller C30S

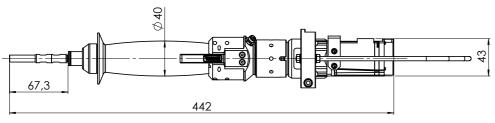
Control signal
Pneumatics

HET Electric handheld screwdriver



Features

- For various applications without auto feeding
- For applications with high process repeatability requirements where a direct measuring system is mandatory
- With vacuum technology option for recessed screwdriving locations



Dimensions and technical data may differ depending on the configuration.

Technical data

Series	0	3	10		30	
Torque range [Nm]	0,2 - 1,5	1 - 3	1-10	1-6,6	8-30	12,5-30
Max. rotation speed [rpm]	2.500	1.500	1500	1500	1200	600
Weight* [kg]	1	,2	2,6		4	
Total length* [mm]	34	40	380		400	
Grip Ø [mm]			Ø40			
Tool holding coupler			1/4" with quick change	e chuck		
Option vacuum			yes			
Option magnetic screwdriving tool			yes			

*With direct drive

Technical changes reserved.



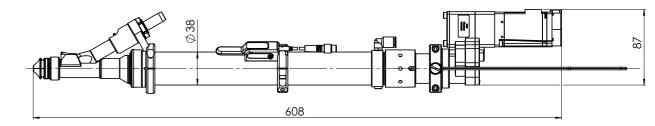
Handheld Screwdriving

HSE

Electric handheld screwdriver for automatic feeding system

Features

- With automatic bit stroke for user assisted application
- For applications without interfering contours/recesses for shank-heavy screws
- With adjustable bit lock stroke for ease of finding the screwdriving location
- For applications with high process repeatabililty requirements where a direct measuring system is mandatory
- With vacuum technology option for recessed screwdriving locations (model HSE-V)
- With magnetic extension screwdriving tool option for slightly recessed screwdriving locations
- Suitable for automatic feeding



Dimensions and technical data may differ depending on the configuration

Technical data

Series Torque range [Nm] Max. rotation speed [rpm] Head diameter [mm] Stroke length [mm] Weight* [kg] Total length* [mm] Grip Ø [mm] Tool holding coupler Option vacuum Option magnetic screwdrving tool

*With direct drive and standard screwdriving head ass'y





	03			10
0,2 - 1,5		1 - 3	1 - 10	1,9 - 6
2.500		1.500	1.500	800
		3 - 15		
	90		90	130
	1,8		2	2,5
	464		480	580
		38		
		1/4" with quick cha	ange chuck	
		yes		
		yes		

Handheld Screwdriving

HSP | HSD | HSV



Pneumatic handheld screwdriver for automatic feeding



Features

- With integrated pneumatic drive for user assisted application
- For applications without interfering contours/recesses for shank-heavy screws
- Torque adjustment via mechanical clutch
- With magnetic extension screwdriving tool option for slightly recessed screwdriving locations
- With vacuum technology option for recessed screwdriving locations (model HSV)
- Swivel arm principle: Feeding during screwdriving
- Suitable for automatic feeding



Dimensions and technical data may differ depending on the configuration.

Technical data

Series	HSP HSD HSV 32			
Torque range [Nm]	0,5 -	- 5,3 0,	5 - 4 0,	5 - 3
Max. rotation speed [rpm]	650) 10	00 1	500
Head diameter [mm]		3 -	14	
Stroke length [mm]	80	92	104	128
Weigth* [kg]	2,6	2,8	2,8	3,3
Total length* [mm]	385	420	445	490
Grip Ø [mm]	40			
Tool holding coupler	1/4" with quick change chuck			
Option vacuum	yes			
Option magnetic screwdriving tool	yes			

*With standard screwdriving head ass'y

Technical changes reserved.

Criteria	HET	HSE	HSP
Parallel arm with table top or wall mounting	\checkmark	\checkmark	~
Linear support arm	\checkmark	\checkmark	\checkmark
Balancer	\checkmark	\checkmark	\checkmark
Vertical mounting	\checkmark	\checkmark	\checkmark
Pistol grip	\checkmark	\checkmark	\checkmark
Foot switch	\checkmark	\checkmark	\checkmark

Linear support arm	HHG7 ESD	HHG20 ESD
Option angle and linear monitoring	\checkmark	\checkmark
Horizontal stroke	200 mm	390 mm
Vertical stroke	400 mm	540 mm
Load capacity	0,8-2,5 kg 2,8-6,5 kg	8-12 kg 12-20 kg
A [mm]	440	700
B [mm]	245	250
C [mm]	940	1250
D [mm]	Ø 110	148
E [mm]	Ø 110	102

Handheld Screwdriving

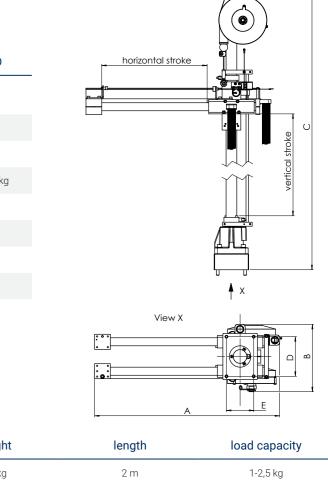
Accessories

Balancer	Ø	weight
Balancer 1-2,5 kg	146 mm	3,2 kg
Balancer 2-4 kg	146 mm	3,2 kg

Pistol grip*	Ø	weight	length	electrical connection
HSE/HET	40x30 mm	0,3	110 mm	M8 4-pole
HSP	38x25 mm	0,4	120 mm	-

*Always with mounting

Technical changes reserved.



2m

2-4 kg



As is well known, the whole is more than the sum of the individual parts. Hence also WEBER's screwdriving systems grow with the requirements that companies impose on automated assembly processes. Fixtured screwdriving technology is used if connection processes are more complex, cycle times are shorter and quality requirements are higher. WEBER's variably configurable fixtured screwdriving

spindles adapt themselves to all screwdriving cases: whether mouthpieces, stroke lengths, sensors or drive units – WEBER offers tailor-made solutions depending on the task and screwdriving process. Nevertheless, the effort to change tools on the screwdriving units remains low – thanks to the tool-free change of the screwdriving head assembly.

Long service life thanks to wearresistant surfaces



Economically viable from 60,000 screwdriving operation per year

 ~ 7



Low moving mass for short cycle times

Fixtured Screwdriving

Overview of fixtured screwdrivers

Configurable stationary screwdriving spindles for your application

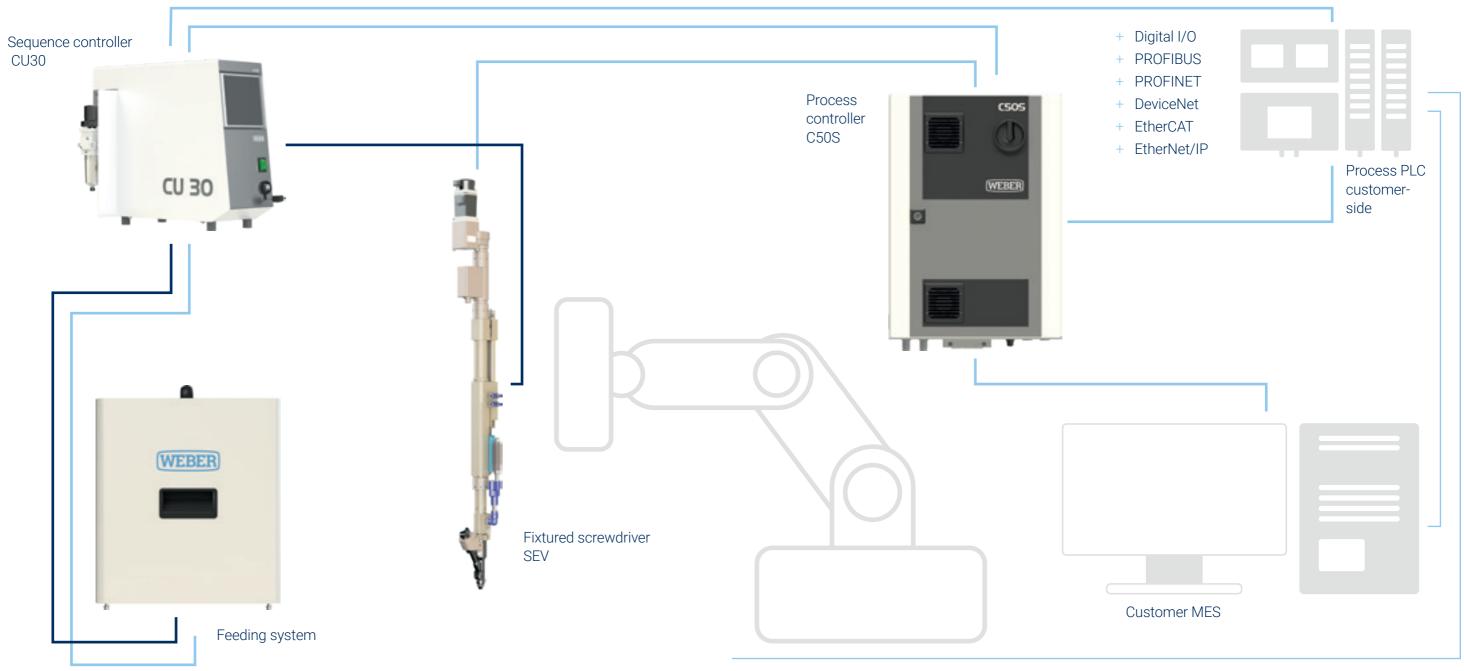
Criteria	SER	SEB	SEV	SEM	SEK	SEV-E	SEV-C	SEV-L	SEV-P
For shank-heavy screws (Head diameter / Shaft length > 1,5 mm)	\checkmark	\checkmark	\checkmark	-	-	\checkmark	\checkmark	\checkmark	~
For head-heavy screws (Head diameter / Shaft length < 1,5 mm)					\checkmark			-	\checkmark
For nuts	-	-	-	\checkmark	-	-	-	-	\checkmark
For inserting / press-fitting	\checkmark	\checkmark	\checkmark	-	-	-	\checkmark	\checkmark	\checkmark
For applications w/o contours/recesses	\checkmark	\checkmark	-	-	-	-	\checkmark	\checkmark	\checkmark
For limited access screwdriving locations	-	-	\checkmark						
For applications with hard-to-reach and extremely recessed screwdriving locations		-	-	\checkmark	\checkmark	\checkmark	-	-	\checkmark
Thread friendly application	\checkmark								
Closed spindle module	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark
Spindle module - open slide design	-	-	-	-	-	\checkmark	-	-	-
With integrated head clearance stroke		\checkmark	-	-	-		-	-	-
With pneumatic bit stroke	\checkmark	-							
With electrical bit stroke	-	-	-	-	-	\checkmark	-	-	-
Low moving mass due to fixed drive motor	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	-	\checkmark	\checkmark	\checkmark
Modular drive concept	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	-	\checkmark	\checkmark
Torque range up to 10 Nm	\checkmark								
Torque range up to 60 Nm	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark		-	-	\checkmark
Torque range up to 120 Nm	\checkmark	-	\checkmark	\checkmark	\checkmark	-	-	-	-
Designed for linear axis applications	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	-	\checkmark	(🗸)
Designed for application with industrial robots	\checkmark	-	\checkmark	\checkmark	\checkmark	\checkmark	-	\checkmark	\checkmark
Designed for LWR applications	-	-	-	-	-	-	\checkmark	\checkmark	\checkmark
Designed for HRC applications	-	-	-	-	-	-	\checkmark	-	-
Swivel arm principle for automatic feeding	\checkmark	\checkmark	\checkmark	√ *	√ *	\checkmark	\checkmark	\checkmark	-
With vacuum technology	-	-	\checkmark						
Pick & Place version	-	-	\checkmark	-	-	-	-	-	\checkmark
Option redundant measuring according to VDI / VDE 2862 sheet 2 category A	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	-	-	\checkmark

*Screwdriving tool ass'y in drawer design, feeding of the fastener during the screwdriving process LWR = Lightweight robot

HRC = Human Robot Collaboration

System overview

Typical fixtured screwdriver set up in your workstation



Positioning device



Modular design

Modular design screwdriving spindles for flexible configuration





Ball bushing

3-finger aligning guide



2-finger aligning guide



Downholder adaptor

with swivel arm



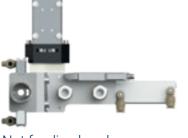
Connecting sleeve



Screwdriving module SEV-E



Screwdriving module SEB



Nut feeding head



Vacuum screwdriving head ass'y



. . Dynamic transducer

MDW





Vacuum module





EC motor with direct drive



EC motor with offset gear



EC motor with inverse gear



EC motor with integrated transducer MDG

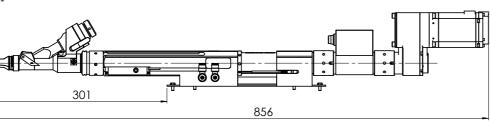
SER





Features

- For applications with accessible locations: use of standard aligning guides
- For shank-heavy screws
- Swivel arm principle: Feeding during screwdriving
- Suitable for automatic feeding



Dimensions and technical data may differ depending on the configuration.

Technical data

03	10	30	60	120
0,3 - 3	1 - 10	3 - 30	6 - 60	12 - 120
2.500	2.500	1.500	1.500	300
3 - 16	5 -21	9 -24	9 -24	9 - 24
approx. 5	approx. 7	approx. 9	approx. 11	approx. 16
70 90 120 190	90 120 160 240	120 160 200	120 160 200	160 200
30 90 180	45 135 270	70 210 420	70 210 420	160 480 960 70 210 420**
11 -18 7,4 - 38 24,4 - 68 89 - 126	4,5 - 33,3 2,3 - 63,3 42,3 - 103,3 89 - 126,4	2,5 - 42,2 42,5 - 82,2 42,3 - 84	2,5 - 42,2 42,5 - 82,2 42,3 - 84	2,5 - 42,2 42,5 - 82,2 42,3 - 84
3/16"	1/4"	5/16"	7/16"	7/16"
	0,3 - 3 2.500 3 - 16 approx. 5 70 90 120 190 30 90 180 11 - 18 7,4 - 38 24,4 - 68 89 - 126	0,3 - 3 1 - 10 2.500 2.500 3 - 16 5 - 21 approx. 5 approx. 7 70 90 120 190 90 120 160 240 30 90 180 45 135 270 11 - 18 7,4 - 38 24,4 - 68 89 - 126 4,5 - 33,3 2,3 - 63,3 42,3 - 103,3 89 - 126,4	0,3 - 3 1 - 10 3 - 30 2.500 2.500 1.500 3 - 16 5 - 21 9 - 24 approx. 5 approx. 7 approx. 9 70 90 120 190 90 120 160 240 120 160 200 30 90 180 45 135 270 70 210 420 11 - 18 7,4 - 38 24,4 - 68 89 - 126 4,5 - 33,3 2,3 - 63,3 42,3 - 103,3 89 - 126,4 2,5 - 42,2 42,5 - 82,2 42,3 - 84	0,3 - 3 1 - 10 3 - 30 6 - 60 2.500 2.500 1.500 1.500 3 - 16 5 - 21 9 - 24 9 - 24 approx. 5 approx. 7 approx. 9 approx. 11 70 90 120 160 240 120 160 200 120 160 200 30 90 180 45 135 270 70 210 420 70 210 420 11 - 18 7,4 - 38 24,4 - 68 89 - 126 4,5 - 33,3 2,3 - 63,3 42,3 - 103,3 89 - 126,4 2,5 - 42,2 42,5 - 82,2 42,3 - 84 2,5 - 42,2 42,5 - 82,2 42,3 - 84

*With direct drive and standard screwdriving head ass'y **Version LAF Low Axial Force

Technical changes reserved.

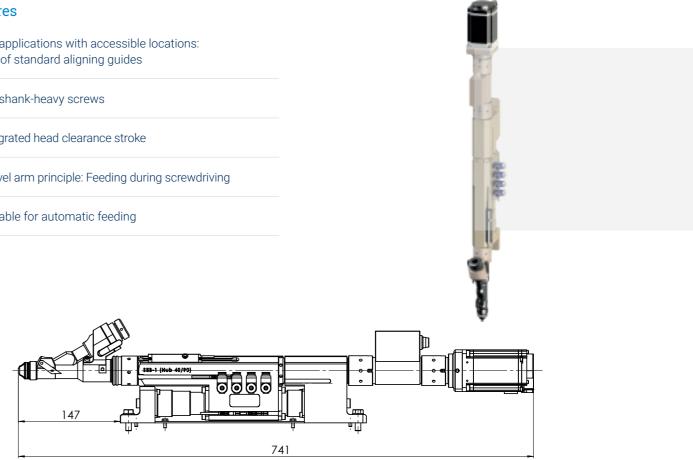


SEB

Fixtured screwdriver with integrated head stroke

Features

- For applications with accessible locations: use of standard aligning guides
- For shank-heavy screws
- Integrated head clearance stroke
- Swivel arm principle: Feeding during screwdriving
- Suitable for automatic feeding



Dimensions and technical data may differ depending on the configuration.

Technical data

60
6 - 60
1.500
9 - 24
approx. 11
120 160 200
70 210 420
2,5 - 42,2 42,5 - 82,2 42,3 - 84
60
115 345 690 N
7/16"

*With direct drive and standard screwdriving head ass'y



SEV For hard to reach screwdriving locations

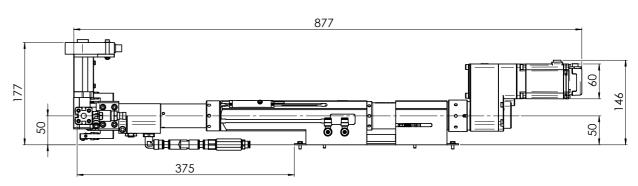


Fixtured Screwdriving

SEM | SEK For nuts and head-heavy screws

Features

- For nut assembly, also for hard to reach screwdriving locations: with vacuum technology
- For head-heavy screws SEK
- For DIN-, flange- and application specific nuts SEM
- Screwdriving head ass'y in pusher design with profile tube, feeding during screwdriving
- Suitable for automatic feeding

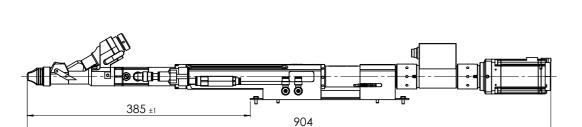


Technical data

Series	03	10	30	60	120
Torque range [Nm]	0,3 - 3	1 - 10	3 - 30	6 - 60	12 - 120
Max. rotation speed [rpm]	2.500	2.500	1.500	1.500	300
Head diameter (SEK) [mm]	3 - 16	5 -21	9 - 24	9 - 24	9 -24
Nut size (SEM)	M2 - M4	M3 - M8	M5 - M10	M5 - M10	M5 - M10
Nut size Ø collar or across corners [mm]	up to 10	up to 15	up to 20	up to 20	up to 20
Weight* [kg]	approx. 5	approx. 7	approx. 9	approx. 11	approx. 16
Bit stroke (intern) [mm]	70 90 120 190	90 120 160 240	120 160 200	120 160 200	160 200
Axial force bit (1 3 6 bar) [N]	30 90 180	45 135 270	70 210 420	70 210 420	160 480 960 70 210 420**
Max. overstroke depending on head diameter [mm]	11 -18 7,4 - 38 24,4 - 68 89 - 126	4,5 - 33,3 2,3 - 63,3 42,3 - 103,3 89 - 126,4	2,5 - 42,2 42,5 - 82,2 42,3 - 84	2,5 - 42,2 42,5 - 82,2 42,3 - 84	2,5 - 42,2 42,5 - 82,2 42,3 - 84
Tool holding coupler	3/16"	1/4"	5/16"	7/16"	7/16"
*With direct drive and standard screwdriv	ving head ass'v				

**Version LAF Low Axial Force

Technical changes reserved.



Features

• For shank-heavy screws

• Suitable for automatic feeding

reduction

• For hard to reach screw locations with complex

interference contours: with vacuum technology

• Swivel arm principle: Feeding during screwdriving

• For requirements of technical cleanliness with particulate

Dimensions and technical data may differ depending on the configuration.

Technical data

Series	03	10	30	60	120
Torque range [Nm]	0,3 - 3	1 - 10	3 - 30	6 - 60	12-120
Max. rotation speed [rpm]	2.500	2.500	1.500	1.500	300
Head diameter [mm]	6,5 - 11	6,5 - 13	9 - 24	9-24	9 - 24
Weight* [kg]	from 5	from 7	from 9	from 11	from 16
Bit stroke (intern) [mm]	70 90 120 190	90 120 160 240	120 160 200	120 160 200	160 200
Axial force bit (1 3 6 bar) [N]	30 90 180	45 135 270	70 210 420	70 210 420	160 480 960 70 210 420**
Max. overstroke depending on head diameter [mm]	11 -18 7,4 - 38 24,4 - 68 89 - 126	4,5 - 33,3 2,3 - 63,3 42,3 - 103,3 89 - 126,4	2,5 - 42,2 42,5 - 82,2 42,3 - 84	2,5 - 42,2 42,5 - 82,2 42,3 - 84	2,5 - 42,2 42,5 - 82,2 42,3 - 84
Tool holding coupler	3/16"	1/4"	5/16"	7/16"	7/16"

*With direct drive and standard screwdriving head ass'y

**Version LAF Low Axial Force

Technical changes reserved.





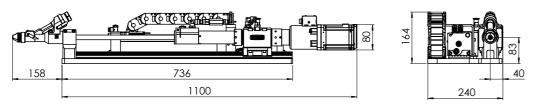
Dimensions and technical data may differ depending on the configuration.

SEV-E For hard to reach screwdriving locations



Features

- For severily recessed screwdriving locations and special applications with extremely long stroke requirements
- Open slide design with pneumatic or electric bit stroke ٠
- For handling shank-heavy screws with swivel arm principle
- With energy chain for cable management
- Three types: right and left version for optimized length (stroke-pneumatic and electric), straight version for optimized width (stroke-pneumatic only)
- Combination possible with SEK or SEM screwdriving ass'y ٠
- Suitable for automatic feeding



Dimensions and technical data may differ depending on the configuration.

Technical data

	30 3 - 3 1.50 9 - 2	0
	1.50	0
	9 - 2	4
lata SEM		
approx. 21 a	approx. 24	approx. 30
\checkmark	-	\checkmark
350	300	350
5 N **	72 217 4	134 N **
500	-	500
	approx. 21	approx. 21 approx. 24

*With direct drive and standard screwdriving head ass'y **+ - 150 N depending on the screwdriving direction





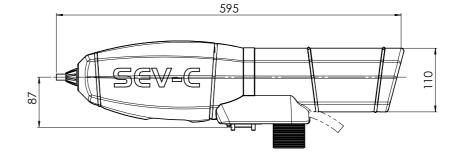
Fixtured Screwdriving

SEV-C

Human Robot Collaboration

Features

- For collaborative HRC applications
- For shank-heavy screws with vacuum technology
- Safety cover and mouthpiece pressure sensor
- Integrated LED strips for process status
- Swivel arm principle: Feeding during screwdriving
- Suitable for automatic feeding



Dimensions and technical data may differ depending on the configuration.

Technical data

Torque range [Nm]	1 - 6
Max. rotation speed [rpm]	800
Head diameter [mm]	6 - 12
Weight* [kg]	approx. 4,8
Bit stroke (intern) [mm]	90 130
Axial force bit (1 3 6 bar) [N]	20 60 120
Max. overstroke depending on head diameter [mm]	up to 35
Tool holding coupler	1/4"
Collaborative mode according to level 4 of ISO TS 15066	\checkmark

*With direct drive, standard screwdriving head ass'y and cable pack





SER-L / SEV-L



Spindle for lightweight robots for automatic feeding



Features

- For lightweight robots and coexisting HRC applications
- For shank-heavy screws
- With vacuum technology option for recessed screwdriving locations (SEV-L)
- Swivel arm principle: Feeding during screwdriving ٠
- Suitable for automatic feeding

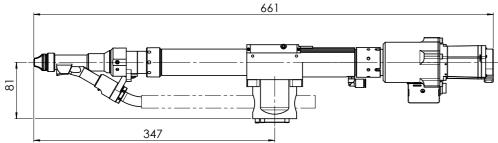
Fixtured Screwdriving

SEV-P

Pick & Place screwdriver for robot applications

Features

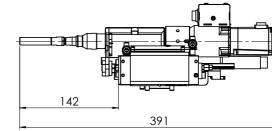
- For use with collaborative lightweight or industrial robots
- For Pick & Place applications with vacuum technology for fasteners of all types
- Automatic tool change with tool identification system using RFID (read & write)
- Force-controlled stroke and active depth measurement through optional head stroke slide
- Suitable for automatic feeding in Pick & Place design



Dimensions and technical data may differ depending on the configuration.

Technical data

Series	SEV-L	SER-L
Torque range [Nm]	1 - 10	1 - 10
Max. rotation speed [rpm]	2500	2500
Head diameter [mm]	6 - 16	6 - 16
Weight* [kg]	ca 3,7	ca 3,6
Bit stroke (spindle intern) [mm]	90 130	90 130
Axial force bit (1 3 6 bar) [N]	20 60 120	20 60 120
Max. overstroke depending on head diameter [mm]	32 - 73,5	32 - 73,5
Tool holding coupler	1/4"	1/4"
Collaborative mode according to level 4 of ISO TS 15066	-	-
Nith direct drive, standard screwdriving head ass'y and cable pack		



Technical data

Series	SEV-P10	SEV-P30	SEV-P60
Torque range [Nm]	1 - 10	3 - 30	6 - 60
Max. rotation speed [rpm]	2.500	1.500	850
Head diameter [mm] / Nut size		as needed	
Weight with / without slide [kg]	4,6 3,5	9,5 8	20 14
Bit stroke (spindle intern) [mm]	5	5	10
Axial force intern bit stroke [N]	5	5	5
Head stroke slide [mm]	50	50	125
Max. screw location recess [mm]	130	180	130
Axial force head stroke [N]	50	50	125
Tool holding coupler	1/4"	5/16"	7/16"
With direct drive			

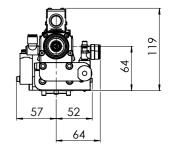
Technical changes reserved.

Technical changes reserved.









Dimensions and technical data may differ depending on the configuration

Inserting and Press-fitting



Connection technology can do more - WEBER offers more. Automation of assembly processes also includes inserting and press-fitting technology. WEBER offers innovative fixtured and handheld systems in this range. With the insertion and press-fitting units for pins, bolts or clips, permanent force-fitting or

force- and form-fitting connections are realized. All systems have automatic feed systems or intelligent controllers and allow high process forces for setting or insertion. Quality control can be achieved during the joining process by a force-path monitoring system. The setting tools are pneumatically powered.



Pneumatic drive or feed requires no separate drive control



Short cycle times due to automatic feeding and swivel arm technology



Various designs for different demanding insertion or press-fitting tasks

Inserting and Press-fitting

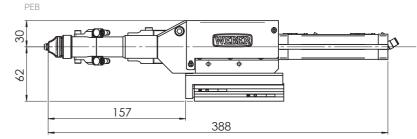
PEB | HPP For various inserting applications

Features PEB

- Adjustable depth and optional insertion force monitoring
- Optional head clearance stroke insertion stroke independent
- Optional for robot application
- Short cycle times due to automatic feeding and swivel arm technology

Features HPP

- Adjustable depth and optional insertion force monitoring
- Linear support arm or balancer for user assisted application
- Faster cycle times possible at manual workstations
- Optional bit lock stroke version



Dimensions and technical data may differ depending on the configuration

Technical data PEB

Model	Standard	Enhanced
Insertion-/press-fitting force [N]	50-600	bis 10.000
Weight [kg]	ca. 2,5	ca. 15
Pneumatic connection [bar]	4 - 8	4 - 8



Technical data HPP

Max. insertion-/press-fitting force [N]	190
Stroke [mm]	90 / 130
Weight [kg]	ca. 2
Pneumatic connection [bar]	4 - 8

Feeding technology

Feeding technology

Overview of feeding systems

Efficient and gentle feeding of fasteners



Automation of assembly processes normally pursues three objectives: efficiency enhancement, quality improvement and cost reduction. To achieve these objectives, the supply of fasteners must be trouble-free and as gentle as possible on the material. WEBER, with its automatic feed systems, achieves a maximum of process quality. The development of these systems requires experience and know-how. WEBER has developed and manufactured individual components for many years, combining them to fully automated feeding systems. After currently more than 30,000 delivered screwdriving and assembly systems with automatic feeding, WEBER is one of the leading companies in this area.



Monitoring with numerous sensors such as presence check and feeder level control





More dann 60 years of experience in feeding technology

Criteria	120	ZEB 240	360	240	ZEL 360	480
For shank-heavy screws	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For head-heavy screws	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For nuts	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For washers	\checkmark	\checkmark	\checkmark	-	-	-
For symmetrical elements	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For non-symmetrical elements		-	-	-	-	-
For elements with adhesive coating	-	-	-	\checkmark	\checkmark	\checkmark
Gentle feeding of parts	-	-	-	\checkmark	\checkmark	\checkmark
For diameter up to 2 mm	\checkmark	-	-	-	-	-
For diameter up to 6 mm	-	\checkmark	\checkmark	\checkmark	\checkmark	-
For diameter up to 12 mm	-	-	\checkmark	-	\checkmark	\checkmark
For diameter up to 14 mm	-	-	\checkmark	-	\checkmark	\checkmark
For diameter up to 16 mm	-	-	\checkmark	-	-	\checkmark
For length up to 22 mm	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For length up to 42 mm	-	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For length up to 48 mm		\checkmark	\checkmark	-	\checkmark	\checkmark
For length up to 70 mm	-	-	\checkmark	-	\checkmark	\checkmark
For length up to 160 mm		-		-	-	\checkmark
For head diameter up to 4 mm	\checkmark	\checkmark	-	\checkmark	-	-
For head diameter up to 12,5 mm	-	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
For head diameter up to 20 mm	-	-	\checkmark	-	\checkmark	\checkmark
For head diameter up to 24 mm	-	-	\checkmark	-	-	~
For head diameter up to 32 mm	-	-	-	-	-	\checkmark
Fill volume/weight	0,3 l / 1,2 kg	1,2 / 5 kg	3,8 l / 17 kg	1,2 / 4 kg	3,01/12 kg	15 /100 kg

Feeding technology

ZEB Bowl feeder



Features

•

• Ideal for long screws, thin washers, head-heavy screws

• Vibratory technique for sorting and feeding fasteners

Abrasion-resistant material for durable operations

• High volume conveying (cycle time up to 0.8 s)

• Universally applicable for fasteners of all types

• Configurable for Pick & Place applications



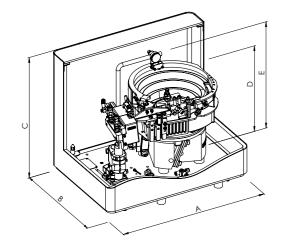
Feeding technology

ZEL

Step feeder

Features

- Suitable for coated and sensitive parts
- Low particulate generation for a high level of technical cleanliness
- Low vibration exit track for low noise level
- Hopper stainless steel (Lift - hardened steel or PE)
- High process stability
- High output volume (cycle time up to 0.8 s)
- Configurable for Pick & Place applications



Technical data

Series	ZEB120	ZEB240	ZEB360
A Width [mm]	480 497 w. SDH*	480 497 w. SDH*	640 650 w. SDH*
B Depth [mm]	340 353 w. SDH*	340 353 w. SDH*	536 547 w. SDH*
C Height [mm]	456 463 w. SDH*	456 463 w. SDH*	602 607 w. SDH*
Weight [kg]	25 w. SDH*	29 w. SDH*	50 w. SDH*
Fill volume [ltr]	0,3	1,2	3,8
Fill weight [kg]	1,2	5,0	17,0
D Height to bowl [mm]	290	300	360
E Height to FSK** [mm]	305	382	440

*SDH =sound enclosure cover, **FSK = feeder level control

ZEB120 ZEB240 ZEB360 Series Screws Head-Ø [mm] 2,0 - 4,0 2,5 - 12,5 6,0 - 24,0 Thread M1 - M2 M2 - M6 M4 - M14 Total length [mm] ≤ 22 ≤ 48 ≤ 73 Nuts Across corner [mm] -≤ 12,5 ≤ 20 Thread ≤ M8 ≤ M10 Height [mm] ≤ 9,5 ≤ 9,5 Pin Pin-Ø [mm] ≤16 ≤8 Length [mm] ≤ 80 ≤ 50 -

Technical data

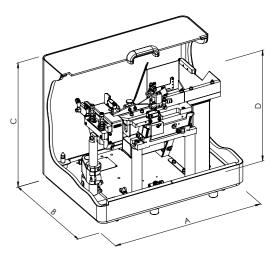
Series	ZEL240	ZEL360	ZEL480
A Width [mm]	480 497 w. SDH*	640 650 w. SDH*	1296 w. SDH*
B Depth [mm]	340	536	1000
C Height [mm]	456 w. SDH*	602 w. SDH*	1141 w. SDH*
Weight [kg]	approx. 60 w. SDH*	approx. 85 w. SDH*	approx. 350 w. SDH*
Fill volume [ltr]	1,2	3,0	15,0
Fill weight [kg]	4,0	12,0	ca. 100,0
D Height to hopper [mm]	397	437	1033

*SDH = sound enclosure cover

Technical changes reserved.







Series	ZEL240	ZEL360	ZEL480
Screws			
Head-Ø [mm]	2,5 - 12,5	6,0 - 20,0	12,0 - 32,0
Thread	M2 - M6	M4 - M12	M6 - M16
Total length [mm]	≤ 42	≤ 73	≤ 160
Nuts			
Across corner [mm]	≤ 12,5	≤ 20	≤ 32,0
Thread	≤ M8	≤ M10	≤ M16
Height [mm]	≤ 9,5	≤ 9,5	≤ 20,0
Pins			
Pin-Ø [mm]	≤8	≤ 14	≤ 24,0
Length [mm]	≤ 48	≤ 73	≤ 160

Feeding technology

Accessories

Optional accessories		ZEB	ZEL
=	Sound enclosure cover w/o hopper opening	v	~
	Basic frame	V	~
	Hopper frame only w. basic frame	~	V
	Feeder level control ZEL	-	V

Feeder level control ZEB

Feeding technology

Accessories Belt driven refill hopper

Features

- Bulk part storage
- Longer refill autonomy (for operators)
- Folding top cover (optional)
- 24V drive for global application
- Compact design

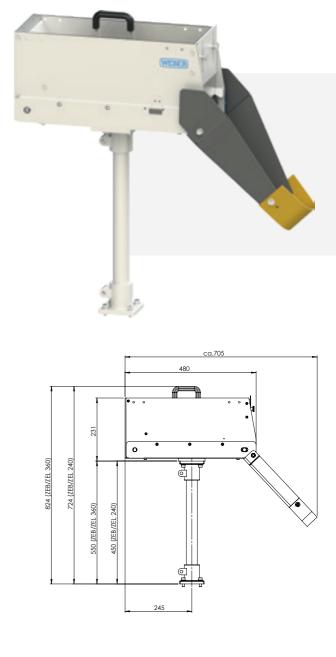
Adjustable output

- Option: level sensor
- Option: lockable

Technical data

Series	BB-04	
Length [mm]	380	
Width [mm]	193	
Height [mm]	201	
Fill volume [ltr]	4	
Max. fill weight [kg]	10	





BB-08	BB-18
480	580
223	273
231	251
8	18
20	45

Control Systems



The controllers that are integrated in our automated screwdriving systems, are basically divided into screwdriving and process control systems. The screwdriving process controller monitors and controls the actual screwdriving process - it ensures that the preset speed, torque and depth are being maintained. In particular, the

controller is important in evaluating the process and documentation of all screwdriving data. Process controllers are responsible for the control of the entire system. For example, they control the stroke movement of the screwdriving spindle, the feeding of fasteners or the communication with peripheral devices.



Ensure optimum coordination of the WEBER components



Process evaluation and documentation of screwdriving/result data



Easy parameterisation

Overview of control systems

Process controller (1/2)

Features	C5S	C30S	C50S
General information			
ESD-compliant	\checkmark	option	option
Remote maintenance via PC	via USB	-	via TCP/IP
Display, parameterisation und Visualisation			
Integrated touch display	-	\checkmark	-
Integrated status leds	\checkmark	-	-
External touch display	-	option	option
Operation and parameterisation via Windows PC	\checkmark	-	\checkmark
Screwdriving programs			
Torque measurement (directly by transducer)	-	\checkmark	\checkmark
Torque measurement (indirectly by motor power)	\checkmark	\checkmark	-
Number of storable screwdriving programs	15	31	255
User definable program levels	7 strategies	13 strategies	25 strategies
User definable application of the program steps (finding, screwdriving, seating, NIO treatment, etc.)	-	-	\checkmark
Gradient screwdriving method (torque and depth)	-	-	\checkmark
Relative torque	-	\checkmark	\checkmark
M360° process	-	-	\checkmark
Results user definable from the program steps	-	- (fixed)	✓ (flexible)
Number of result values	-	4	5
Forming or pre-torque output	-	\checkmark	\checkmark
Digital depth sensor	\checkmark	\checkmark	\checkmark
Connection additional analog depth sensor	\checkmark	\checkmark	\checkmark
Redundant measurement acc. to VDI 2862, Cat. A	-	option	option
Set parameters via customer interface	-	\checkmark	\checkmark
Automatic release	w/o overrun time	incl. overrun time	incl. overrun time
Hardware connections			
Ethernet RJ45	-	option	\checkmark
RS232	-	option	-
USB Master (for USB-Stick)	-	\checkmark	-
USB Slave (for PC)	\checkmark	\checkmark	-
Interfaces for customer control			
Digital I/O	\checkmark	option	option
Field bus interfaces	-	option	option
Curve recording			
Visualisation / Display of the screwdriving curves on the device	-	√	\checkmark
Curve memory in the controller	last result only	last result only	1000

Overview of control systems

Process controller (2/2)

Features	C5S	C30S	C50S
Statistics			
Logbook	-	\checkmark	\checkmark
Limit values	-	-	\checkmark
Sigma values	-	-	\checkmark
Results	-	\checkmark	\checkmark
Optional documentation possibilities			\checkmark
On external system	-	-	option
Results (numeric values, part ID)	-	\checkmark	\checkmark
Process parameters	-	\checkmark	\checkmark
Curves	-	-	\checkmark
Via MySQL database	-	\checkmark	\checkmark

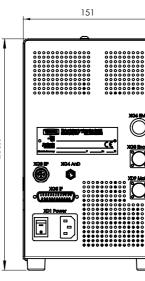
Control systems

C5S

Process controller for simple screwdriving tasks

Features

- Easy configuration and testing via PC software
- Compatible with all WEBER fixtured screwdrivers, as well as handheld screwdrivers type HET, HSE
- Intuitive software with configurable programs and definable current consumption torque
- Extensive diagnostic and monitoring options of the spindle and interface



Sequence controller

Features	C10S	C15S	CU30
General information			
ESD-compliant	-	-	\checkmark
Possible remote maintenance via PC	-	-	\checkmark
Emergency stop can be integrated by customer	\checkmark	\checkmark	\checkmark
Integrated display	\checkmark	\checkmark	\checkmark
Integrated feeder vibration control	\checkmark	\checkmark	\checkmark
Pneumatics integrated	-	-	\checkmark
Hardware connections			
USB Slave (for PC)	-	-	\checkmark
RJ45 for field bus	-	-	option
Digital interface to C30S / C50S	-	-	option
Interfaces for customer control			
Digital I/O	-	-	\checkmark
Field bus interfaces	-	-	option
Madels 0100 and 0150 and he pasibilize protection with fraction events			

Models C10S and C15S can be easily integrated with feeding systems.

The CU30 is a high-quality sequence control with integrated pneumatics and PLC, which combines extensive functions and many options in a compact device.

Technical changes reserved.

Technical data

Supply	230 V, Type: IEC connection with L, N, F
E-safety class	Safety class 1 (L, N, PE)
Drives	100 / 400 / 750 Watt
Processes	7 different process cycles
Programs	15 programs based on an individually p
Customer interface Inputs Outputs	Digital I/O Automatic, program no., start, confirm No error, ready to start, OK, NOK, depth
Weight	7,8 kg
Dimensions	266 / 152 / 332 mm (H / W / D, without
Safety class	IP30

Technical changes reserved.





PE, 230 V ± 10% / 50 - 60 Hz

parameterized process sequence

n error ih reached

ut plug)

C30S





Features

- Integrated system software for configuration and control
- Compatible with all WEBER fixtured screwdrivers, as well as handheld screwdrivers type HET, HSE
- Integrated touch display for easy use and configuration
- Supports transducers for precise torque and angle ٠ measurement
- MySQL database connection optionally possible for extensive documentation
- Communication customer interface via field bus module

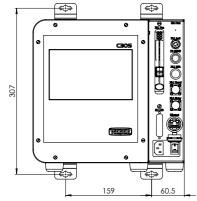
Control systems

C50S

Process controller for high complex screwdriving tasks

Features

- Individual process flow with latest processes configurable
- Gradient screwdriving method (moment, depth), relative moment as well as M360° method
- Individual export of parameters and results
- MySQL database connection optionally possible for extensive documentation
- Communication customer interface via field bus module
- High IT security standard, interface monitoring and diagnostic functions



Technical data

Supply	Standard 230 V, Type: IEC connection with L, N, PE, 230 V \pm 10% / 50 $-$ 60 Hz Option 115 V, Type: IEC connection with L, N, PE, 115 V \pm 10% / 50 $-$ 60 Hz
E-safety class	Safety class 1 (L, N, PE)
Drives	100 / 400 / 750 Watt
Processes	13 different process cycles
Programs	31 programs based on an individually parameterized process sequence
Interfaces	Digital I/O, RS232, PROFIBUS, PROFINET, DeviceNet, EtherCAT, EtherNet/IP
Weight	7,8 kg
Dimensions	280 / 255 / 280 mm (W / D / H, without plug)
Safety class	IP30

Technical changes reserved.

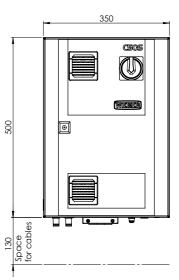
Technical data

Supply	Standard 230 V, Type: IEC connection w
E-Safety class	Safety class 1 (L, N, PE)
Drives	100 / 400 / 750 Watt
Programs	255 programs with up to 25 individual p
Interfaces	Digital I/O, RS232, Profibus, Profinet, De
Weight	20 kg
Dimensions	350 / 250 / 500 mm (W / D / H, without
Safety class	IP54

Technical changes reserved.







500

with L, N, PE, 230 V ± 10% / 50 – 60 Hz

process steps

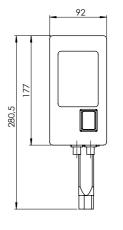
eviceNET, EthernetCAT, EtherNet/IP

ut plug)

Control systems

Sequence controller





General features

- Integrated feeder vibration control
- LCD display with text display and password protection

Features C10S

 Compatible with ZEB feeder and handheld screwdriver type HSP

Features C15S

- Compatible with ZEB / ZEL feeders and handheld screwdrivers type HET / HSE
- Customer interface with inputs and outputs
- Depth shut-off and torque shut-off
- Optional emergency stop & screw presence

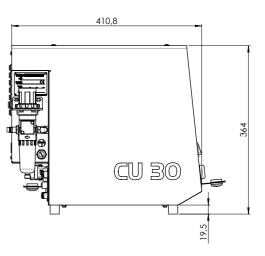


Control systems

CU30 Sequence controller

Features

- Compact sequence controller with integrated pneumatics and PLC
- Compatible with all WEBER feeding systems as well as handheld and fixtured screwdrivers
- Optional integrated proportional valve for HSE handheld screwdriver
- Integrated touch display and software for configuration and management



Technical data

Supply	100-230 V, Type: IEC connection with L,
E-safety class	Safety class 1 (L, N, PE)
Power input	Average 40 Watt
Weight	13,5 kg
Compressed air supply	6 bar / 0,6 MPa
Dimensions	364 / 226 / 287 mm (H / W / D, without
Safety class	IP30

Technical changes reserved

Technical data

Feeder vibration control	Frequency and amplitude adjustable
Supply	230 V, Type: IEC connection with L, N, PE, 230 V \pm 10% / 50 $-$ 60 Hz
Supply (optional)	115 V Type: connection with L, N, PE, 115 V \pm 10% / 50 $-$ 60 Hz
Power input	< 115 Watt
E-safety class	Safety class 1 (L, N, PE)
Weight	2,8 kg
Dimensions	178 / 92 / 192 mm (H / W / D, without plug)
Safety class	IP30

Technical changes reserved..





L, N, PE, 230 V ± 10% / 50 – 60 Hz

ut plug)

Accessories

Transducer



Features

- Torque and angle recording in one transducer
- Integrated measurement amplifier
- Evaluation of the transmitted signals by the screwdriving controller
- Non-contact transmission of torque from the shaft to the housing
- Measurement of the angle of rotation via encoding disc and light barrier
- Can also be used redundantly for category A fittings according to VDI / VDE 2862
- Cable connections upwards or downwards facing

Control systems ACCESSOTIES M30

Features

- Applicable for both active and passive sensors + screw joint simulator as well as MDW dynamic transducer or rotating transducer
- Small size and weight as well as battery operation make it very good for mobile use
- 10 sets of parameters (calibration) can be stored for different sensors
- Data logger for up to 600 measurement values with time and date stamp
- High resolution at 1/1000th of a second
- Trigger input for external control
- Battery powered (4 x AA) or with optional AC adapter
- USB and RS-232 interface for data transfer or print outs

Technical data

Model	MD	W03	MDW10	MDW	30	MDW60	MDW120
Measurement range [Nm]	0,1 - 1	0,3 - 3	1 – 10	1,5 - 15	3 - 30	6 - 60	12 - 120
Accuracy class				0,15 %			
Repeatability	0,05 %						
Usable torque	130 %						
Limit torque	200 %						
Handling temperature range [°C]	+10 +55						
Control actuation	off <2V, on >3,5 V						
Angle of rotation	2 tracks, 360 pulses						
Angular resolution	0,5°						
Max. rotation speed [rpm]	5.000						
Safety class when installed	IP 54						

Technical data			
	Model		
	Dimensions (L x W x H) [mm]		
	Weight without cable and batteries [g]		
	Handling temperature range [°C]		

Safety class

Technical changes reserved.

Technical changes reserved.





M30

40 x 100 x 200 330 +5 bis +45 IP 40

Torque accuracy of screwdriving systems for automatic feeding

Pneumatic drive



with current torque

EC drive



Accuracy ± 15 % for cmk ≥ 1,67 (10-30 %)* ± 15 % for cmk ≥ 2 (30-100 %)*

- Process controller: C5S / C30S
- Accuracy ± 15 % for cmk ≥ 1,67 (10-30 %)* ± 15 % for cmk ≥ 2 (30-100 %)*

Standard deviation ± 3 %

Standard deviation ± 3 %

EC drive with reaction transducer MDG



- Process controller: C30S / C50S
- EC servo drive with integrated reaction transducer MDG (> 0,5 Nm)
- Accuracy ± 10 % for cmk ≥ 1,67 (10-30 %)* ± 10 % for cmk ≥ 2 (30-100 %)*

Standard deviation ± 2 %

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EC drive with transducer MDW



Process controller: C30S / C50S

EC servo drive with transducer and angle measurement MDW

Accuracy

± 7 % for cmk ≥ 1,67 (10-30 %)* ± 7 % for cmk ≥ 2 (30-100 %)*

Standard deviation \pm 1,4 %

Systems



As we all know, the whole is more than the sum of its parts. In the same way, WEBER screwdriving systems grow with the requirements that our customers have for automated assembly processes. Fixtured screwdriving systems are used when joining processes become more complex, cycle times become shorter and quality requirements become higher. The variably configurable

fixtured screwdriving spindle from WEBER adapt to all screwdriving applications: Whether mouthpiece, stroke lengths, sensors or drive technology - WEBER Screwdriving Systems offers customized solutions for all applications and screwdriving processes. Retooling on the screwdriving units is made easy by the screwdriving head assembly which can be changed without tools.

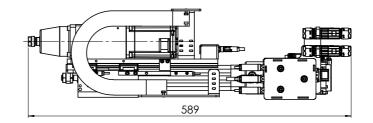
Systems

TSS

Setting system for sandwich structures

Features

- The installation of plastic bosses in lightweight materials is possible with or without pre-hole
- User defined process parameters with monitoring and evaluation
- Feasibility study and evaluation of completed joints at the WEBER laboratory
- High resolution process results
- For tasks with accessibility from one side only
- Plastic bosses as fastening element or as usable fastening point for self-tapping screws



Technical data

Compact spindle design [mm] H x D x W	630 x 185 x 165
Spindle weight [kg]	approx. 13
EC drive [rpm]	up to 5.000
Max. axial force [N]	1.400
Cycle time (w/o cooling) [s]	from 3

Technical changes reserved.













Locating

Penetration / Melting

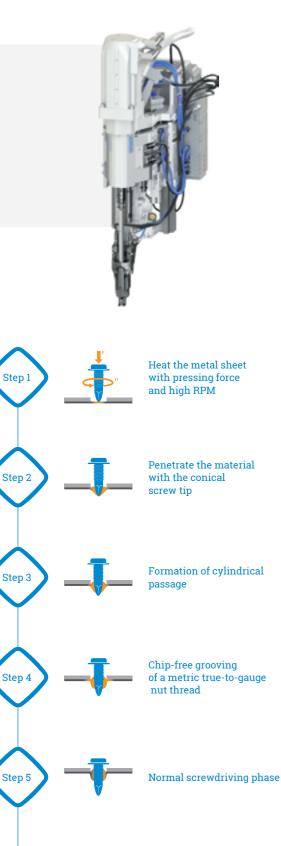
Dwell time with down force

Cooling / Tool retract

Systems

RSF25

Robot-assisted screwdriving system

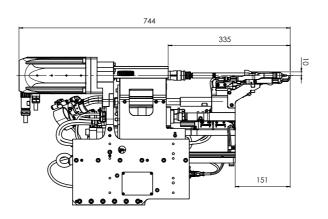


Tighten the screws to the set torque Flowdrilling Technology

- One-sided accessibility
- For assembling different materials with varying thicknesses
- Low heat joint forming
- High loosening torque and excellent vibration resistance

WEBER RSF Flow Drilling Joining System

- Active jaws to prevent screw tilting
- Manual quick tool change
- Flexible spindle design



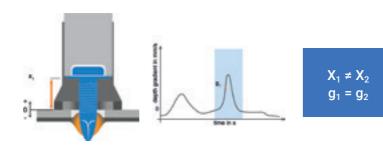
Technical data

Torque [Nm]	up to 15
EC drive [rpm]	up to 8.000
Max. axial force (at 6 bar) [N]	up to 3.600
Holding down force (at 6 bar) [N]	up to 1.400
Cycle time [s]	from 1,6

Technical changes reserved.

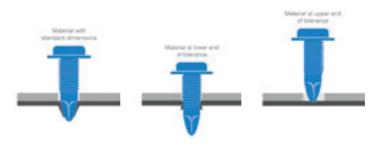


The right combination of strength and speed is the decisive factor for flow drilling joining technology: while high forces and speeds are essential for flow drilling, very little force is required during thread forming work since the thread pitch of the screw will determine the speed of penetration.



Patented WEBER Boost function

Variations in material and temperature can cause situations where the sets of parameters specified in the laboratory do not perform optimally in practice. To date, any recalibration work required has been a very time-consuming process that

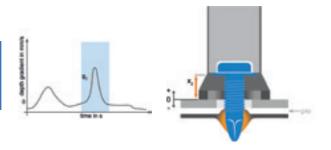


Automatic pre-punch compensation

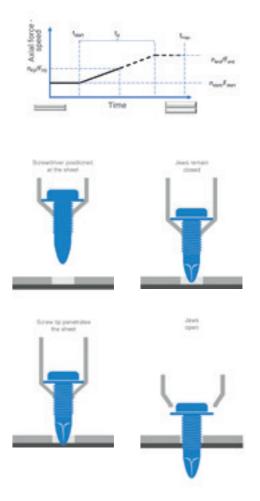
The screw is guided by the jaws right up to the point at which the screw tip has penetrated the material. Only then are the jaws opened and the screwdriving procedure can then begin.

- Increased flexibility in production due to reduced number of variants
- Increase process reliability
- Reduced NOK rate
- Reduced abrasion

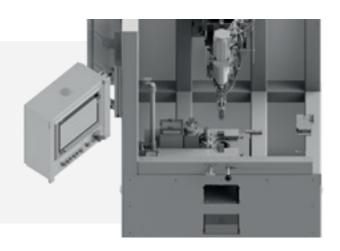
The patented WEBER depth gradient identifies changes in depth while the screw is breaking through the material and therefore always switches between these two processing steps at the optimum moment.



regularly needs to be adjusted to the ongoing production situation. To solve this problem, WEBER uses the new boost feature offered by the RSF25. This increases both axial force and speed automatically until the depth gradient is achieved.



System for function testing



Features

- Defined, repeatable test sequence
- Direct OK/NOK evaluation
- Automated output of a detailed test report
- Different test scenarios can be selected

Systems

SBM

Inserting system for blind rivet nuts and bolts

Features

- Suitable for automatic feeding
- Engaging and forming via 2 separate EC drives
- Automatic removal and ejection of blind rivet nuts in the event of structural component faults
- Monitoring of the threading process via motor encoder and force measurement
- Standard set screw according to DIN threaded mandrel
- Quick-change system for threaded mandrel
- Applicable in all working directions even if only accessible from one side



Testing the feeder and spindle in a continuous cycle

The components and processes of feeding screws to the spindle are tested for correct functioning. Depending on customer requirements, up to 500 elements can be run in one test cycle.



Torque test with CMK evaluation

For the tightening/torque testing, the functional capability of the sensor installed in the spindle is checked and verified with a measurement. The CMK values of the system are evaluated automatically.



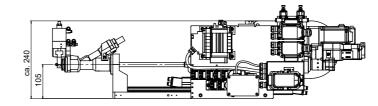
Force measurement of the downholder force

First, the axial force of the screwdriver on the spindle is tested. In the second step, the force with which the downholder presses the screwdriving spindle onto the part before the fastener touches the part surface is recorded.



Screwdrivings and torque test

The test screwdrivings examine a complete process with feeding, screwdriving and reloading. After the last screwdriving process, the test cycle is completed with a torque test to verify the maximum rotational speed.

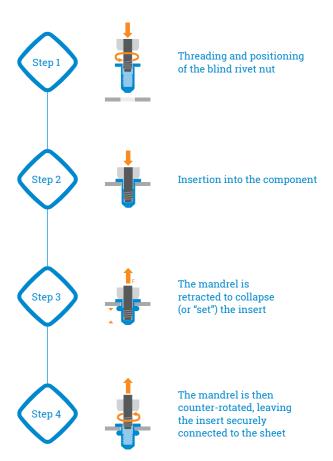


Technical data

Inserting force [kN]	up to max. 25	
Inserting stroke [mm]	8	
Standard head stroke [mm]	approx. 75	
Weight [kg]	approx. 24	
Processable sizes	M5, M6, M8, M10	
Processable shapes	Round and hexagonal head, other shapes on request	









Let's put it this way:

"Everything in business is negotiable except quality." This could be a direct quote from us. Because for over six decades, WEBER has set standards in the development and manufacturing of automatic handheld screwdrivers and fixtured screwdriving systems. More than 400 employees worldwide ensure that this will continue to be the case in the future. That's a promise.

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